

Home Search Collections Journals About Contact us My IOPscience

Explicit solutions and linearisation of certain non-linear evolution equations-bilinear transformation method

This article has been downloaded from IOPscience. Please scroll down to see the full text article. 1987 J. Phys. A: Math. Gen. 20 3047 (http://iopscience.iop.org/0305-4470/20/10/047) View the table of contents for this issue, or go to the journal homepage for more

Download details: IP Address: 129.252.86.83 The article was downloaded on 31/05/2010 at 19:42

Please note that terms and conditions apply.

## COMMENT

## Explicit solutions and linearisation of certain non-linear evolution equations—bilinear transformation method

N Ravi, K M Tamizhmani and M Lakshmanan

Department of Physics, Bharathidasan University, Tiruchirapalli 620 023, India

Received 4 August 1986, in final form 10 November 1986

Abstract. Considering the complex Burgers, Cheng chemical reaction and Liouville equations, we show that through Hirota's bilinearisation method solutions can be obtained straightforwardly. We also show that these systems are exactly linearisable.

It is well known that Hirota's bilinear transformation method (Hirota 1971, 1976, Matsuno 1984) is the most convenient one, among direct methods, of finding solutions to non-linear evolution equations. In this comment we wish to apply this bilinearisation procedure to linearise exactly and obtain explicit solutions of the complex Burgers, Cheng chemical reaction and Liouville equations in a natural way.

We first consider the complex Burgers equation in the form

$$u_t + \mathbf{i}u_{xx} + 4uu_x = 0. \tag{1}$$

Recently, Bruschi and Ragnisco (1985) have proved that (1) admits an infinite number of constants of motion in involution. By the dependent variable transformation

$$u = g/f \tag{2}$$

(1) can be rewritten in the bilinear form

$$(D_t + \mathrm{i}D_x^2)gf = 0 \tag{3}$$

and

$$4D_{x}gf - iD_{x}^{2}ff = 0.$$
 (4)

Here,  $D_x$  and  $D_t$  are the usual bilinear operators defined by

$$D_x^m D_t^n ab = \left(\frac{\partial}{\partial x} - \frac{\partial}{\partial x'}\right)^m \left(\frac{\partial}{\partial t} - \frac{\partial}{\partial t'}\right)^n a(x, t)b(x', t') \Big|_{\substack{x = x' \\ t = t'}}$$
(5)

Since  $g = \frac{1}{2}if_x$  is a solution of (4), (3) becomes

$$(D_t + iD_x^2)f_x f = -2iD_x(f_t - if_{xx})f = 0.$$

Thus

$$f_t - \mathbf{i} f_{xx} = 0 \tag{6}$$

holds, and thereby an exact linearisation of (1) is effected. From the above analysis, it is clear that if f is a solution of the Schrödinger equation (6), then  $g = \frac{1}{2}if_x$  in (2) immediately implies the celebrated Cole-Hopf transformation in the complex form, which solves the complex Burgers equation (1).

0305-4470/87/103047+03\$02.50 © 1987 IOP Publishing Ltd 3047

To obtain the explicit solutions of (1), we expand f and g as a formal power series in the parameter  $\epsilon$ :

$$f = 1 + \sum_{n=1}^{\infty} \varepsilon^n f_n \qquad g = \sum_{n=0}^{\infty} \varepsilon^n g_n.$$
<sup>(7)</sup>

Truncating the series in (7) at n = 1 and 2, we can easily obtain one and two solitary wave solutions of (1), respectively, in the form

$$u = \frac{\exp(\eta_1)}{1 - (2i/p_1) \exp(\eta_1)}$$
(8)

and

$$u = \frac{\exp(\eta_1) + \exp(\eta_2)}{1 - (2i/p_1) \exp(\eta_1) - (2i/p_2) \exp(\eta_2)}$$
(9)

where  $\eta_{j} = p_{j}x - ip_{j}^{2}t$ , j = 1, 2.

It is of interest to note that the above type of solutions (8) and (9) exist for the class of equations  $L_q K = \text{constant} \times K^{N-1} K_x$ , where  $N \ge 2$  and  $L_q$  is the *q*th-order linear differential operator in 1+1 dimensions, as noted by Cornille (1982).

Next, we consider Cheng's equation (1984)

$$U_x = -aUV \qquad V_t = bU_x \tag{10}$$

describing the dynamics of photosensitive molecules when a light beam passes through them. In (10), a and b are the absorption and the proportionality constants, respectively. Also, the variables U and V are the light intensity and density of the molecules, respectively.

Introducing the transformations

$$V = (1/a)(\log f)_x$$
  $U = g/f$  (11)

in (10), we obtain the bilinearised equations

$$D_x g f + g f_x = 0 \tag{12}$$

and

$$(1/a)(D_x D_i f f) - b D_x g f = 0.$$
(13)

In addition, we make the transformations

$$f = 1 + \exp \theta$$
  $g = \exp \tilde{\theta}$  (14)

in (12) and (13), and find that

$$g = (-1/ab)\theta_i. \tag{15}$$

But from (12), we observe that  $g_x = 0$  and hence (15) leads to the linear wave equation  $\theta_{xt} = 0$ . Utilising the solution of the linear wave equation  $\theta = P(x) + Q(t)$ , where P(x) and Q(t) are arbitrary, in (11) we obtain

$$U = -(1/ab)Q_t [1 + \exp(P(x) + Q(t))]^{-1}$$
  

$$V = (1/ab)P_x \exp(P(x) + Q(t))[1 + \exp(P(x) + Q(t))]^{-1}$$
(16)

which is a solution of (11). The general solution of Cheng's equation (10) follows by setting  $g(x) = \exp(P(x))$ ,  $h(t) = \exp(-Q(t))$  (Tamizhmani and Lakshmanan 1986).

3048

Finally, we consider the well known Liouville equation (Rogers and Shadwick 1982 and references therein)

$$u_{xt} - e^{\mu} = 0.$$
 (17)

On using

$$u = \log V \tag{18}$$

(17) can be rewritten as

$$VV_{xt} - V_x V_t - V^3 = 0. (19)$$

With the dependent variable transformation

$$V = g/f^2 \tag{20}$$

(19) can be written in the following form:

$$D_x D_t gg = 0 \qquad \qquad f_{xt} = 0 \tag{21a}$$

and

$$2f_x f_t = g. \tag{21b}$$

Solving (21), we find that

$$f(x, t) = A(x) + B(t)$$
<sup>(22)</sup>

and

$$g(x,t) = 2A_x B_t \tag{23}$$

where A(x) and B(t) are arbitrary functions. From (22), (23) and (20), (18) becomes

$$u = \log\left(\frac{2A_x B_t}{(A+B)^2}\right)$$
(24)

which is the well known general solution of (17).

Thus we have proved that the Hirota bilinearisation procedure straightforwardly gives the general solutions of all the above non-linear evolution equations, exactly linearising them in this process.

## References

Bruschi M and Ragnisco O 1985 J. Math. Phys. 26 943

Cheng H 1984 Stud. Appl. Math. 70 183

Cornille H 1982 J. Phys. A: Math. Gen. 15 L529

Hirota R 1971 Phys. Rev. Lett. 27 1192

----- 1976 Bäcklund Transformations, the Inverse Scattering Methods, Solitons, and their Applications (Lecture Notes in Math. **515**) ed R M Miura (Berlin: Springer)

Matsuno Y 1984 Bilinear Transformation Methods (New York: Academic)

Rogers C and Shadwick W F 1982 Bäcklund Transformations and their Application (New York: Academic) Tamizhmani K M and Lakshmanan M 1986 J. Math. Phys. 27 2257